

9/24/19

ITEM
21

The approximation of the goal and the Representative approximation of the proximity to the goal.

When dealing with matters that (are deemed to be) only approachable asymptotically, one of the glaring problematics is how to represent how close you are to the goal.

The identity of the precise proximity between the agent and the goal can, itself, ~~only~~ at best, be attained asymptotically. This gives rise to a kind of asymptotic recursion, constituted by a chain of movements and representations of movement,

one being the micro to the other macro, where the real movement is out of representatio reach, and all ~~such~~ movements are those of representation

The axiom, it seems, for this theory is that representations of real objects are in continuous asymptotic development toward the absolute identification of that object.

Not only is the movement towards absolute identification asymptotic, ~~but so is the movement of mapping~~ but so is the increasing accuracy of the mapping of the proximity between a representation-of-the-real and the real.

Once the mapping of the proximity is in question, the subject must figure the real proximity between the representation-of-the-real and the real (RotR to be used from now on).

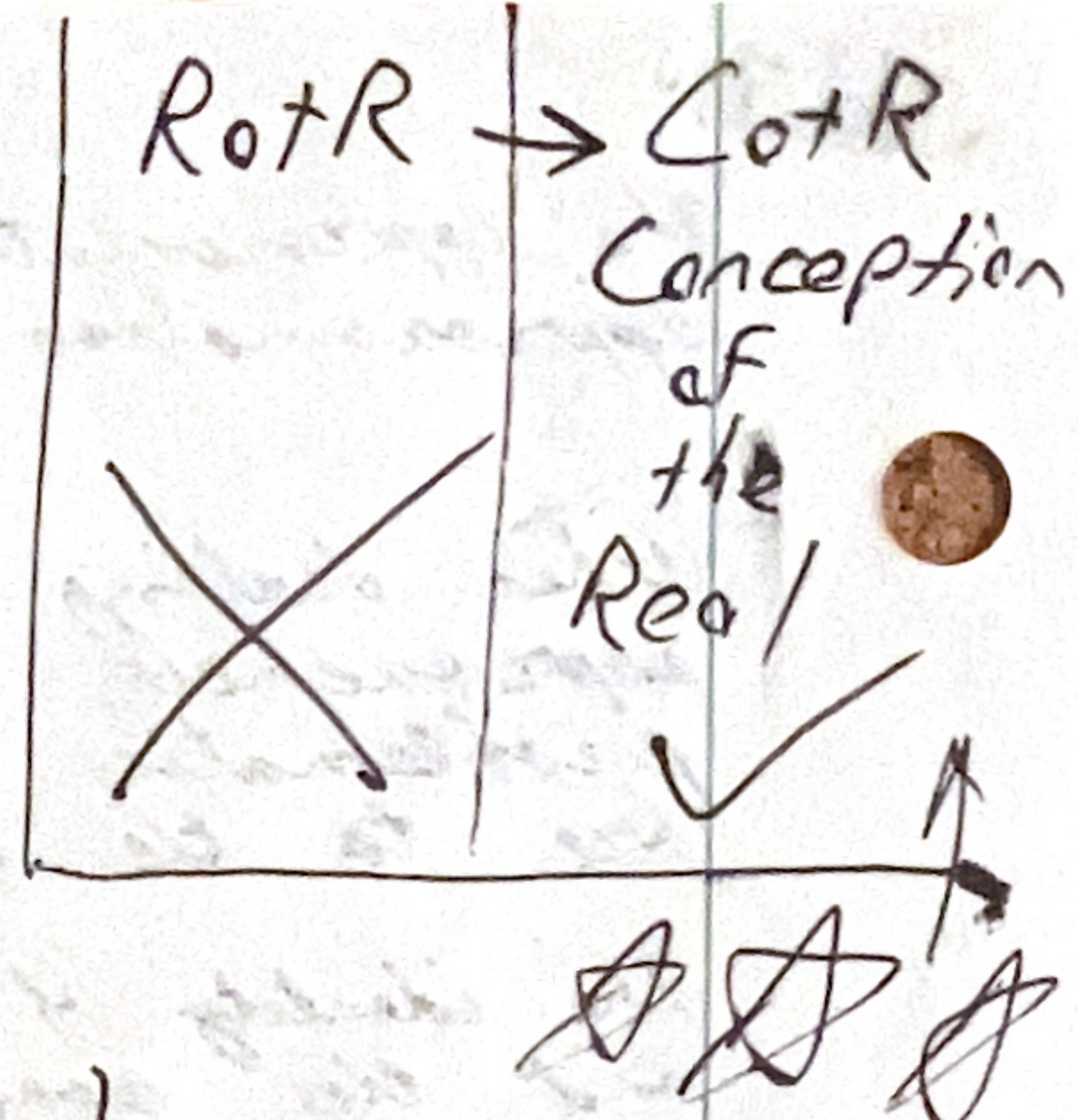
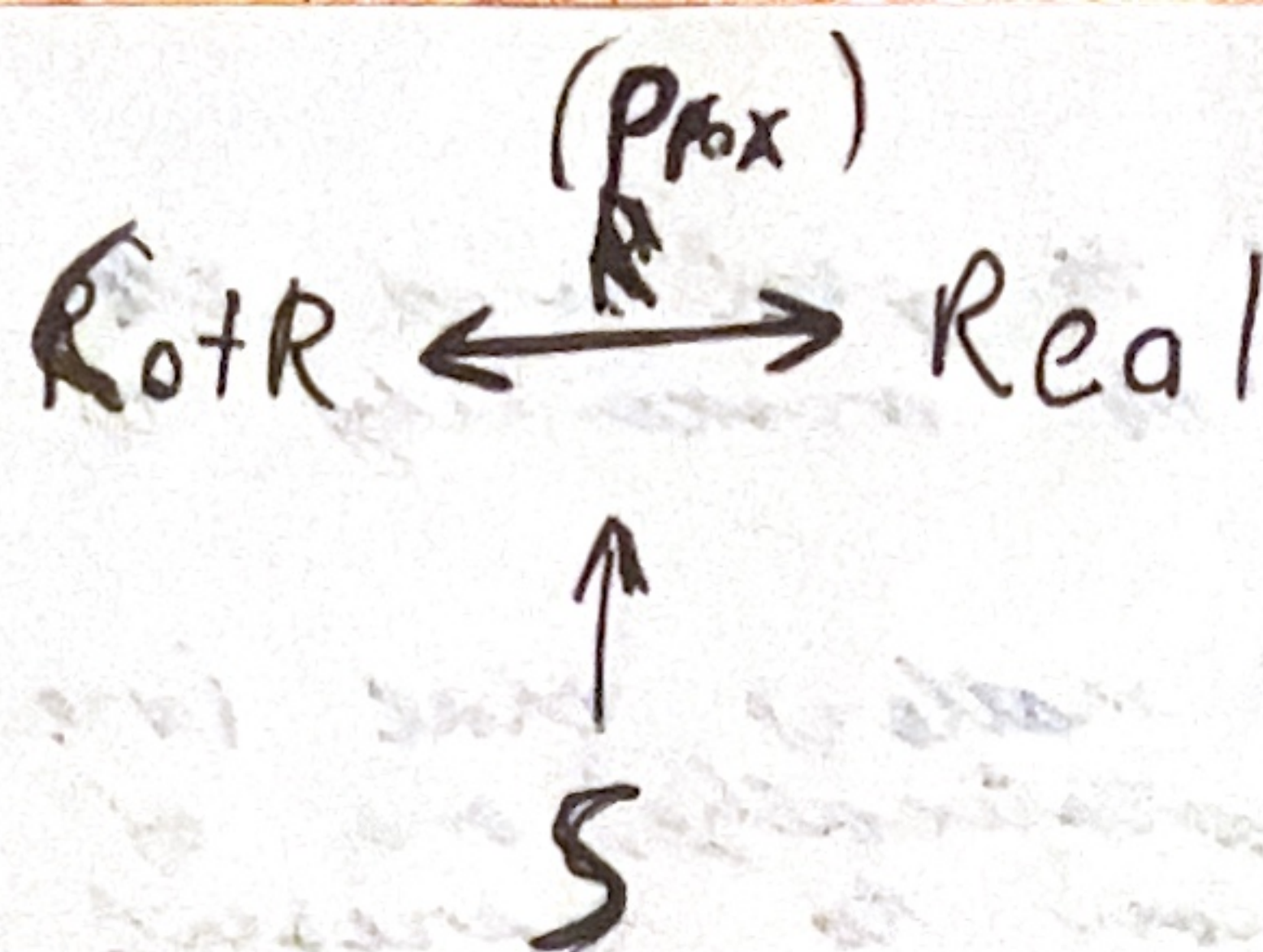
~~And, once the~~ in order to gauge the real proximity, ~~which can only be~~ the identification of which can, likewise, only be approached asymptotically, the subject must figure the proximity between the

A. representation of the proximity between the RotR and the real

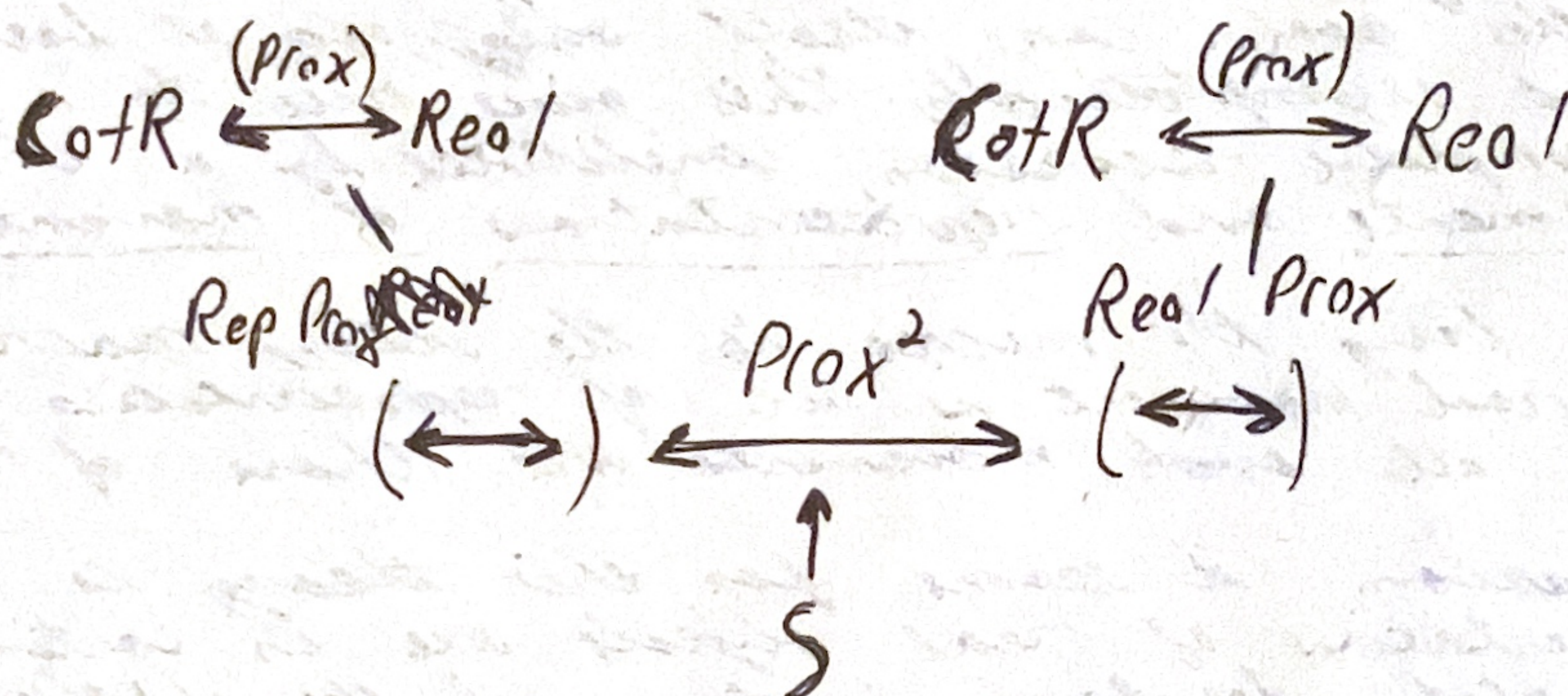
and

B the proximity of between the RotR and the real.

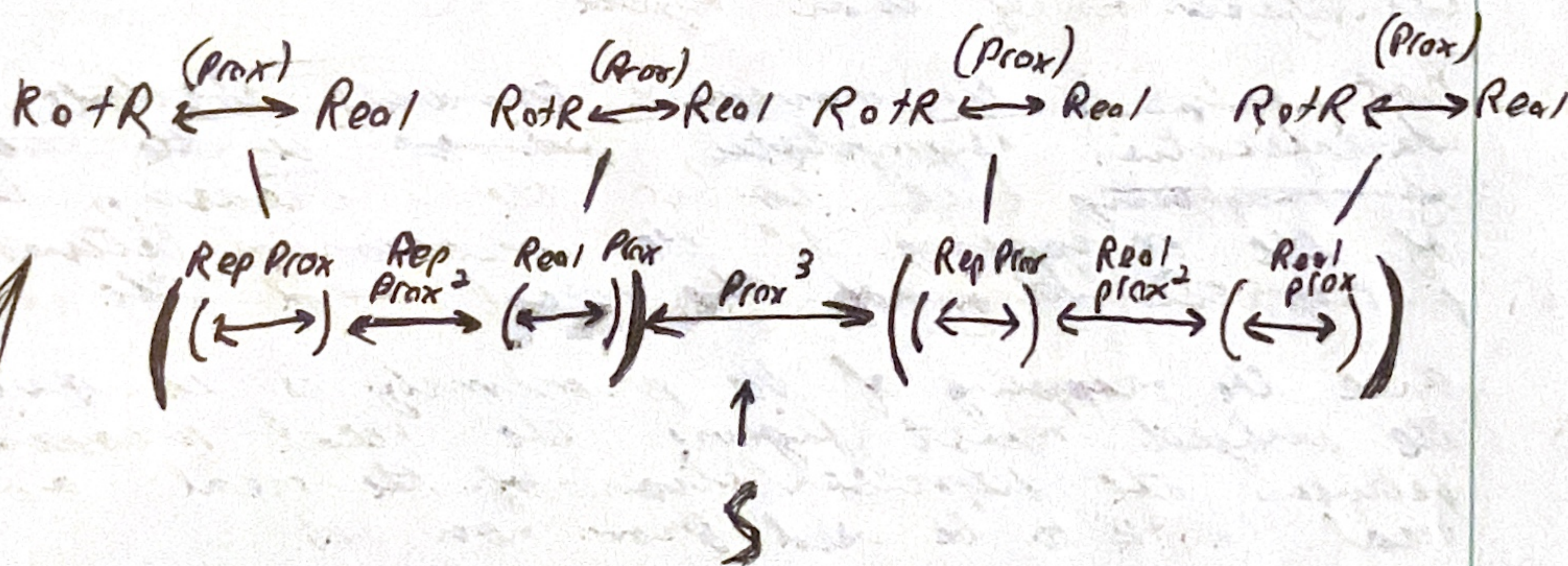
①



②



③



★ All of the $(RotR \leftrightarrow Real)$ $\bar{S}$ at the top are the SAME, refer to the same initial epistemic cleft.